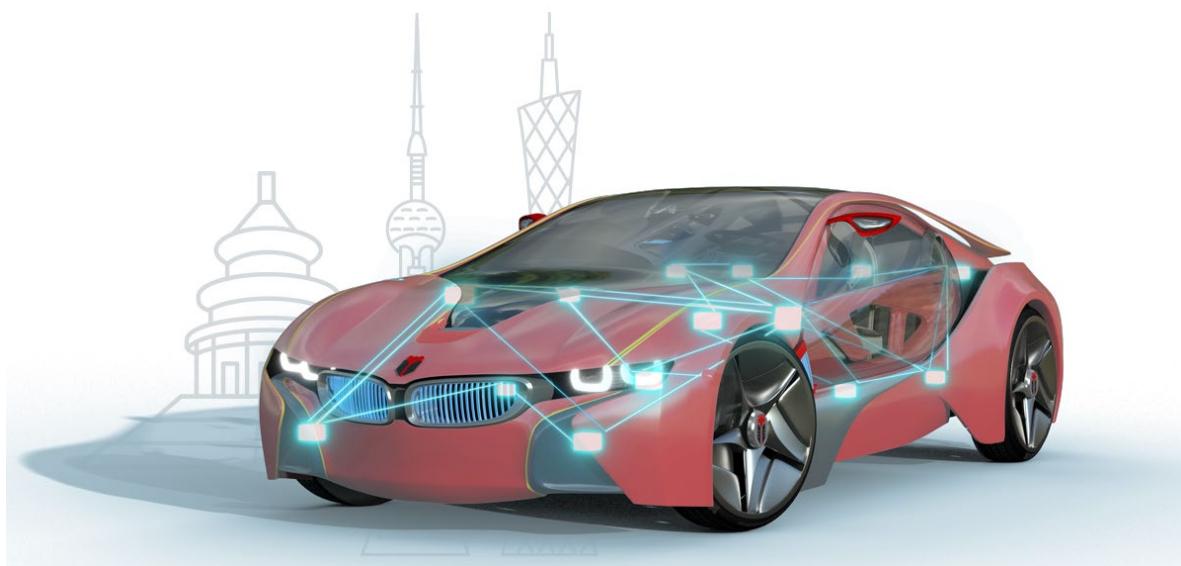




知从木牛基础软件英飞凌 TC4X 产品手册  
ZC.MUNIU BASIC SOFTWARE PRODUCT  
MANUAL BASED ON INFINEON TC4X

知从木牛基础软件平台  
ZC.MuNiu Basic Software Platform



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## 1 功能概述 FUNCTIONAL OVERVIEW

知从.木牛（ZC.MuNiu）为汽车电子控制器产品开发，提供完整的基础软件平台解决方案。该产品参考 AUTOSAR、OSEK 等国际规范，有基于 AUTOSAR ATOP 架构的上位机配置工具，支持上汽、一汽、吉利、广汽、长安、长城等整车厂通讯、诊断、网络管理、启动刷新规范。

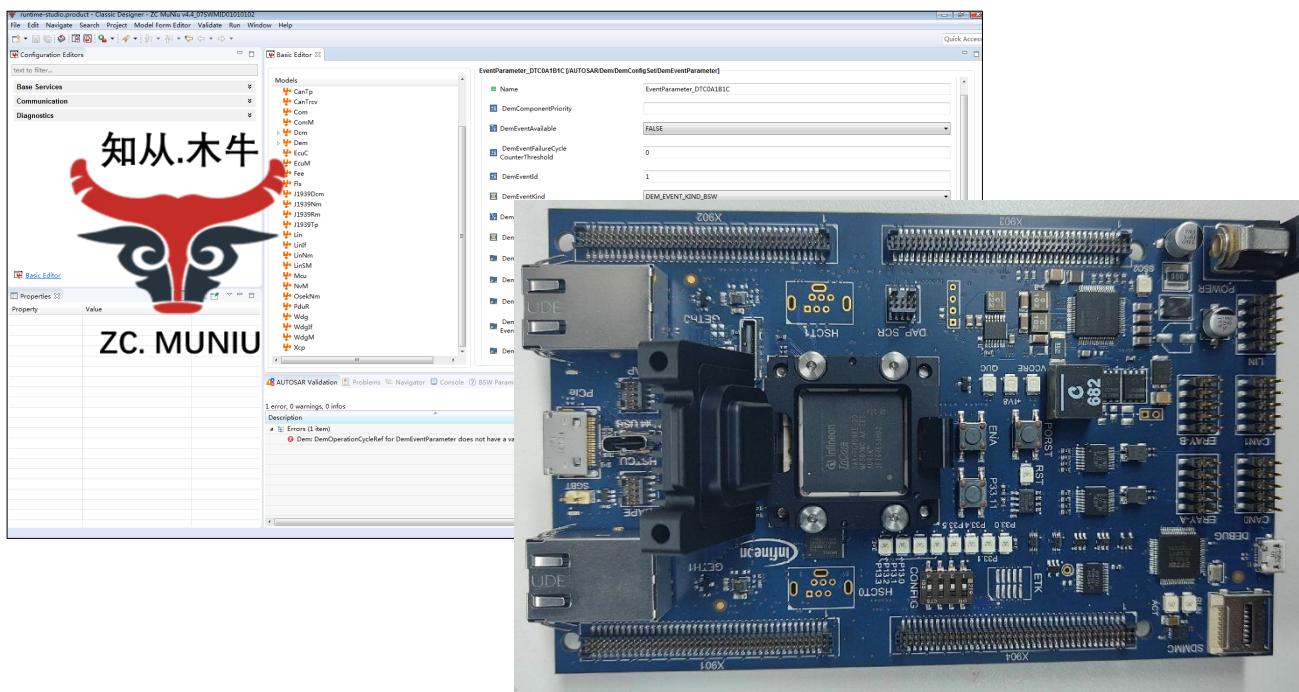
ZC.MuNiu provides a complete basic software platform solution for the development of automotive electronic control units. The product refers to international standards such as AUTOSAR and OSEK, and includes a configuration tool for the upper machine based on the AUTOSAR ATOP architecture, supporting communication, diagnosis, network management, and bootloader and refresh specifications for major vehicle manufacturers such as SAIC Motor, FAW, Geely, GAC Group, Changan Automobile, and Great Wall Motors.

英飞凌 AURIX TC4x 系列微控制器基于 TriCore 1.8 内核，为下一代 ADAS、汽车 E/E 架构和日趋复杂的汽车应用软件架构而设计。英飞凌 AURIX TC4x 系列微控制器支持高速通信接口（ETH 以太网和），为客户提供了新的汽车 E/E 架构所需的性能、吞吐量和灵活性。英飞凌 AURIX TC4x 系列微控制器具备高安全性，符合 ISO 21434 信息安全标准，并能够支持 ISO26262 标准 ASIL-D 功能安全等级应用。

Infineon AURIX TC4x series microcontroller is based on the TriCore 1.8 core and designed for the next generation of ADAS, automotive E/E architecture, and increasingly complex automotive application software architecture. The Infineon AURIX TC4x series microcontrollers support high-speed communication interfaces (ETH Ethernet), providing customers with the performance, throughput, and flexibility required for new automotive E/E architectures. The Infineon AURIX TC4x series microcontroller complies with ISO 21434 information security standard, and can support ISO26262 standard ASIL-D functional safety level application.

上海知从科技作为英飞凌的全球重要合作伙伴和 PDH，为 AURIX TC4x 系列微控制器提供了基础软件平台，主要包括：多核操作系统、通讯协议栈（CAN\LIN）、诊断协议栈（UDS\J1939）、网络管理（OSEK\AUTOSAR）、标定协栈（XCP\CCP）、存储协议栈、复杂驱动模块等，配套知从的 Bootloader 刷新程序和上位机工具，可以根据不同的客户项目要求进行配置和再开发。知从科技提供基础软件产品的同时，也提供控制器基础软件功能实现的开发服务。

Shanghai ZC is important global partner and PDH of Infineon, provides the basic software platform for AURIX TC4x series microcontroller. Mainly includes: multi-core operating system, communication protocol stack (CAN/LIN), diagnostic protocol stack (UDS/J1939), network management (OSEK/AUTOSAR), calibration protocol stack (XCP/CCP), storage protocol stack, complex driver modules, etc., along with ZC's bootloader refresh program and upper machine tool, which can be configured and redeveloped according to different customer project requirements. While providing basic software products, ZC also offers development services for the implementation of control unit basic software functions.



AURIX TC4X 木牛基础软件平台  
ZC.MUNIU BASIC SOFTWARE PLATFORM FOR AURIX TC4X

## 2 应用领域 APPLICATION FIELD

木牛基础软件平台可应用于使用英飞凌 TC4x 系列芯片的汽车电子控制器产品开发。例如：  
ZC.MuNiu Basic Software Platform can be applied to the development of automotive electronic control unit products using the Infineon TC4x series chips. For example:

- 新能源整车控制器  
New Energy Vehicle Controller
- 域控制器  
Zone Controller
- 智能驾驶控制器  
Intelligent Driving Controller

### 3 配置环境 CONFIGURATION TOOL

| 配置环境                             |                                   |
|----------------------------------|-----------------------------------|
| Configuration Environment        |                                   |
| <b>Hardware (Chip)</b>           | TC4D9XE                           |
| <b>Compilers Supported</b>       | Tasking_1.1r8                     |
| <b>Evaluation Hardware</b>       | KIT_TC4D9XE_COM_TRB_S             |
| <b>Debugger</b>                  | lsystem IC5700 (winIDEA 9.21.150) |
| <b>Configuration Tools</b>       | Muniu_v5.1.3                      |
| <b>Configuration Environment</b> | Win10 64bit                       |

| Tasking_1.1r8 编译器选项              |   |
|----------------------------------|---|
| Tasking_1.1r8 Compiler Options   |   |
| <b>编译选项<br/>Compiler Options</b> | <pre>-cs --dep-file="\$(*)F.d" --misrac-version=2004 - D__CPU__=tc49x -DAPP_SW=AURIX3G_MCAL_APP - DAURIX3G_MCAL_APP=1U "-fD:/ Demo/TriCore Debug (TASKING)/TASKING_C_C__Compiler-Include_paths_-l_.opt" -- iso=99 --c++14 --language=+volatile --strict --fp-model=1 - O2 --tradeoff=1 -g -Ctc49x -Y0 -N0 -Z0 --user- mode=hypervisor</pre> |
| <b>链接选项<br/>Linker Options</b>   | <pre>--lsl-file="../Lcf_Tasking_Tricore_Tc.lsl" -WI-Oc -WI-OL -WI-Ot - WI-Ox -WI-Oy -WI--map- file="\${BuildArtifactFileBaseName}.map" -WI-mc -WI-mf -WI-mi -WI-mk -WI-ml -WI-mm -WI-md -WI-mr -WI-mu --no- warnings= -WI--error-limit=42 --fp-model=2 -lrt --lsl-core=vtc --force-c++ -Ctc49x</pre>  |

## 4 开发背景 DEVELOPMENT BACKGROUND

AUTOSAR 组织成立于 2003 年，主要由欧洲汽车制造商、部件供应商及其他电子、半导体和软件系统公司联合建立。致力于为汽车工业开发一个开放的、标准化的软件架构；希望大家“在标准上合作，在应用上竞争”提高基础平台的稳定，降低成本，提高控制器产品开发质量和速度。2006 年底发布了 2.1 版规范，2008 年发布 3.1 版本开始产品化；后续逐步增加了功能安全，以太网等内容，目前广泛使用 2014 年后发布的 4.2.1 和 4.2.2 版本，以及 4.3.1 版本。

The AUTOSAR organization was established in 2003, primarily by European car manufacturers, parts suppliers, and other electronic, semiconductor, and software system companies. It is dedicated to developing an open, standardized software architecture for the automotive industry; the goal is for everyone to "cooperate on standards and compete in applications," improving the stability of the basic platform, reducing costs, and enhancing the quality and speed of controller product development. The 2.1 version of the specification was released at the end of 2006, and the 3.1 version was released in 2008, marking the beginning of productization; subsequently, functionalities such as functional safety and Ethernet were gradually added. The widely used versions are the 4.2.1 and 4.2.2 released after 2014, as well as the 4.3.1 version.

汽车在电动化、网联化、智能化的大趋势下，电子电器部件日益增多，电气结构越加复杂，整车开发周期不断缩短。平台化、智能化的基础软件起到至关重要。

With the trend of electrification, networking, and intelligence in the automotive industry, the number of electronic and electrical components is increasing, the electrical structure is becoming more complex, and the development cycle of the whole vehicle is continuously shortening. The platform-based, intelligent basic software plays a crucial role.

知从·木牛（ZC.MuNiu）为汽车电子控制器产品开发，提供完整的基础软件平台解决方案。该产品符合 AUTOSAR、OSEK 等国际规范，有基于 AUTOSAR ATOP 架构的上位机配置工具，支持上汽、一汽、吉利、广汽、长安、长城等整车厂通讯、诊断、网络管理规范。该平台主要包括：操作系统、通讯协议栈（CAN\LIN）、诊断协议栈(UDS\J1939)、网络管理（OSEK\AUTOSAR）、标定协栈（XCP\CCP）、存储协议栈、复杂驱动模块等，配套知从的 Bootloader 刷新程序和上位机工具，可以根据不同的客户项目要求进行配置和再开发。

ZC.MuNiu provides a complete basic software platform solution for the development of automotive electronic control unit products. The product complies with international standards such as AUTOSAR and OSEK, and has an upper machine configuration tool based on the AUTOSAR ATOP architecture, supporting communication, diagnosis, and network management standards for major vehicle manufacturers such as SAIC, FAW, Geely, GAC, Changan, and Great Wall. The platform mainly includes: operating system, communication protocol stack (CAN/LIN), diagnostic protocol stack (UDS/J1939), network management (OSEK/AUTOSAR), calibration protocol stack (XCP/CCP), storage protocol stack, complex driver modules, etc., along with ZC's bootloader refresh program and upper machine tool, which can be configured and redeveloped according to different customer project requirements.

知从科技提供基础软件产品的同时，也提供符合 ASPIRE Level 3 流程和功能安全 ASIL B/D 要求的控制器基础软件功能实现的开发服务，SBC 芯片、BCCIC 芯片各种复杂驱动软件的定制开发。同时，集成知从科技的功能安全产品 SafetyFrame，可以满足功能安全要求。

While providing basic software products, ZC also offers development services for the implementation of controller basic software functions that comply with the ASPIRE Level 3 process and functional safety requirements of ASIL B/D. It also provides custom development of various complex driver software for SBC chips and BCCIC chips. At the same time, integrating ZC's functional safety product SafetyFrame can meet functional safety requirements.

知从科技掌握 AUTOSAR 平台软件的开发和应用核心技术，提供本地现场支持，质量好，速度快，成本低。

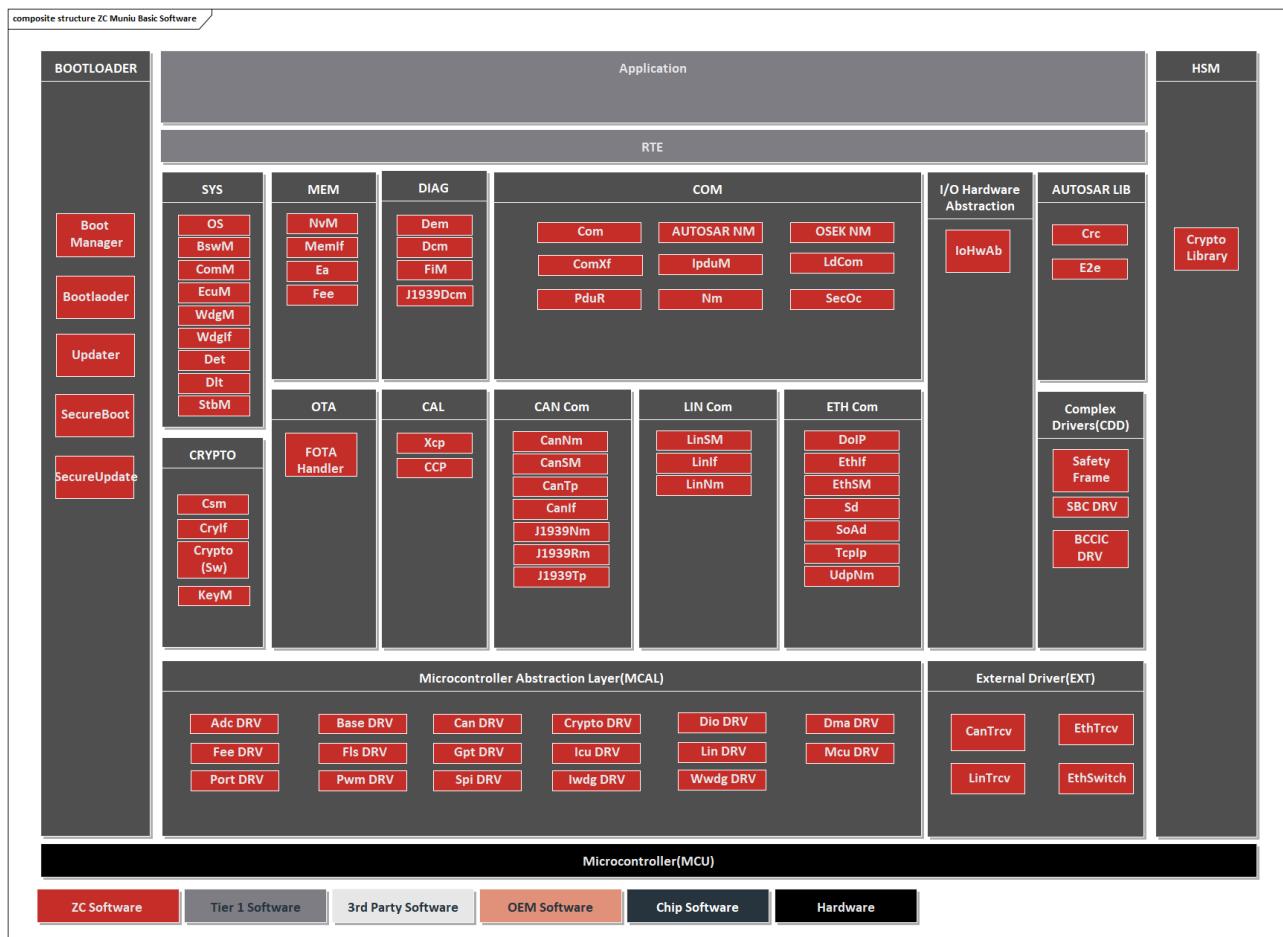
ZC has mastered the core technology of development and application of AUTOSAR platform software, providing on-site local support, with high quality, fast speed, and low cost.

## 5 功能描述 FUNCTIONAL DESCRIPTION

### 5.1 产品特点 Product Feature

- 符合 AUTOSAR 4.3.1 版本 Compliant with AUTOSAR 4.3.1 version
- ARTOP 架构上位机配置工具，最高适配 AUTOSAR 4.4.0 版本  
ARTOP architecture upper machine configuration tool, compatible up to AUTOSAR 4.4.0 version
- 多核操作系统 Muti-Core Operating System
- 通讯协议栈 Communication Protocol Stack (CAN\LIN)
- 诊断协议栈 Diagnostic Protocol Stack (UDS\J1939)
- 网络管理 Network Management (OSEK\AUTOSAR)
- 标定协议栈 Calibration Protocol Stack (XCP\CCP)
- 存储协议栈 Storage Protocol Stack
- 加密模块 Cryptography Module (CRYPTO)
- 复杂驱动定制开发 Custom Development of Complex Drivers
- 工程服务 Engineering Services

## 5.2 软件架构 Software Architecture



知从木牛基础软件平台架构  
ZC.MUNIU BASIC SOFTWARE PLATFORM ARCHITECTURE

| 模块<br>Module   | 子模块<br>Submodule | 描述<br>Description        |
|--|------------------|--------------------------|
| 微控制器底层驱动<br>Microcontroller Abstraction Layer (MCAL) | Can DRV          | CAN 驱动<br>CAN Driver     |
|  | CanFD DRV        | CANFD 驱动<br>CANFD Driver |
|  | Lin DRV          | LIN 驱动<br>LIN Driver     |
|  | Adc DRV          | Adc 驱动<br>Adc Driver     |
|  | Base DRV         | Base 驱动<br>Base Driver   |

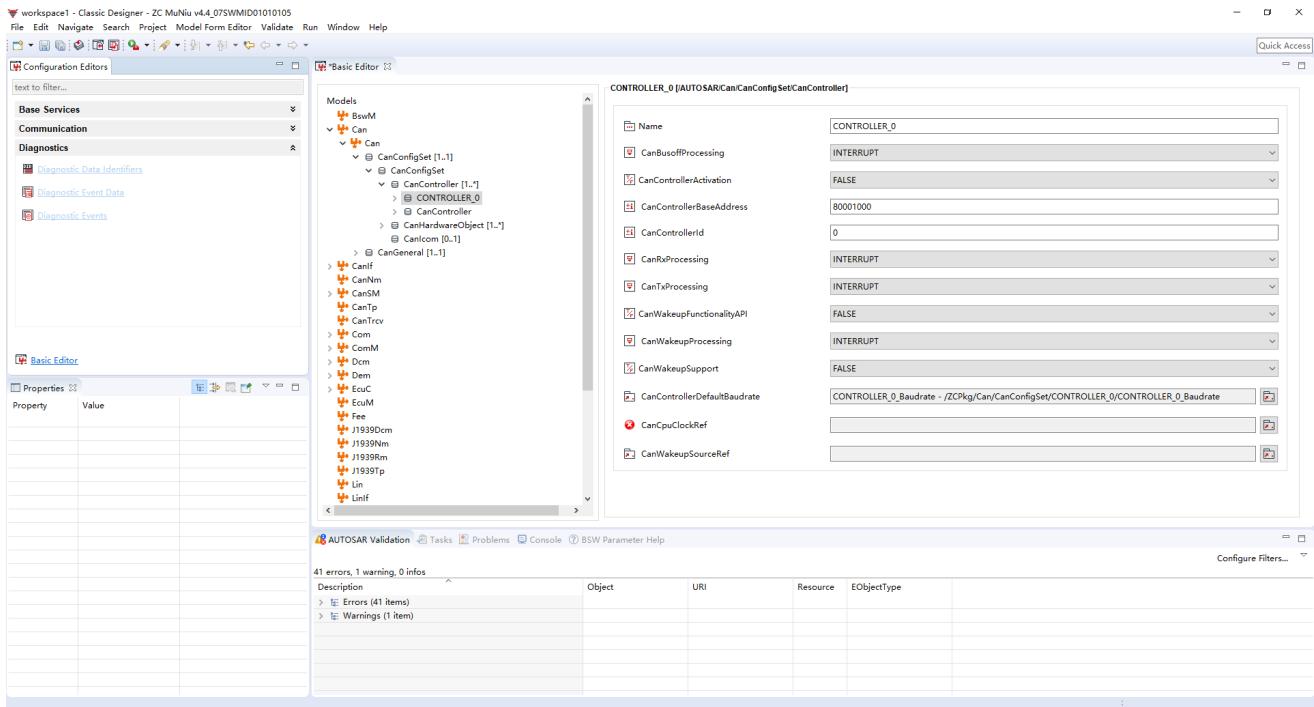
| 模块<br>Module  | 子模块<br>Submodule | 描述<br>Description  |  |
|---|------------------|--|--|
| <b>微控制器底层驱动集成包</b><br><b>Microcontroller Abstraction Layer Integrated Package</b> | Crypto DRV       | Crypto 驱动<br>Crypto Driver   |  |
|   | Dio DRV          | Dio 驱动<br>Dio Driver   |  |
|   | Fee DRV          | Fee 驱动<br>Fee Driver   |  |
|   | Fls DRV          | Fls 驱动<br>Fls Driver   |  |
|   | Gpt DRV          | Gpt 驱动<br>Gpt Driver   |  |
|   | Icu DRV          | Icu 驱动<br>Icu Driver   |  |
|   | Mcu DRV          | Mcu 驱动<br>Mcu Driver   |  |
|   | Port DRV         | Port 驱动<br>Port Driver   |  |
|   | Pwm DRV          | Pwm 驱动<br>Pwm Driver   |  |
|   | Spi DRV          | Spi 驱动<br>Spi Driver   |  |
|   | Iwdg DRV         | Iwdg 驱动<br>Iwdg Driver   |  |
|   | Wwdg DRV         | Wwdg 驱动<br>Wwdg Driver   |  |
| <b>外部底层驱动</b><br><b>External Low-Level Driver (EXT)</b>                           |                  | 可集成第三方 MCAL 的集成工程服务包<br>ZC has an Integrated engineering service package that can be integrated with third-party MCAL. |  |
|   | CanTrcv DRV      | CAN收发器驱动<br>CAN Transceiver Driver   | 实现外部硬件组件的 AUTOSAR 基础软件模块<br>Implement the AUTOSAR basic software module for communication with external hardware |
|   | EthTrcv          | Eth收发器驱动<br>Eth Transceiver Driver   |  |
|   | LinTrcv          | Lin收发器驱动   |  |

| 模块<br>Module                                    | 子模块<br>Submodule | 描述<br>Description                                      |
|---|------------------|--|
|   |                  | components.  |
| <b>系统服务</b><br><b>System Service (SYS)</b>      | EthSwitch        | Lin Transceiver Driver<br>Eth交换机驱动<br>Eth Switch       |
|   | OS               | 操作系统<br>Operating System                               |
|   | BSWM             | 基础软件模式管理<br>Basic Software Mode Management             |
|   | COMM             | 通信管理<br>Communication Management                       |
|   | DET              | 开发错误追踪<br>Development Error Tracking                   |
|   | ECUM             | ECU管理<br>ECU Management                                |
|   | WDGIF            | 看门狗接口<br>Watchdog Interface                            |
|   | WDGM             | 看门狗管理器<br>Watchdog Manager                             |
|   | Dlt              | 诊断日志和跟踪<br>Diagnostic Log and Trace                    |
|   | StbM             | 同步时基管理器<br>Synchronized Time-Base Manager              |
| <b>诊断服务</b><br><b>Diagnostic Service (DIAG)</b> | Dcm              | 诊断通信管理器<br>Diagnostic Communication Manager            |
|   | Dem              | 诊断事件管理器<br>Diagnostic Event Manager                    |
|   | FiM              | 功能抑制管理器<br>Functional Suppression Manager              |
|   | J1939Dcm         | J1939诊断通信管理器<br>J1939 Diagnostic Communication Manager |
| <b>存储服务</b>                                     | EA               | EEPROM抽象层  |
|   |                  | 实现非易失性存储管理的基   |

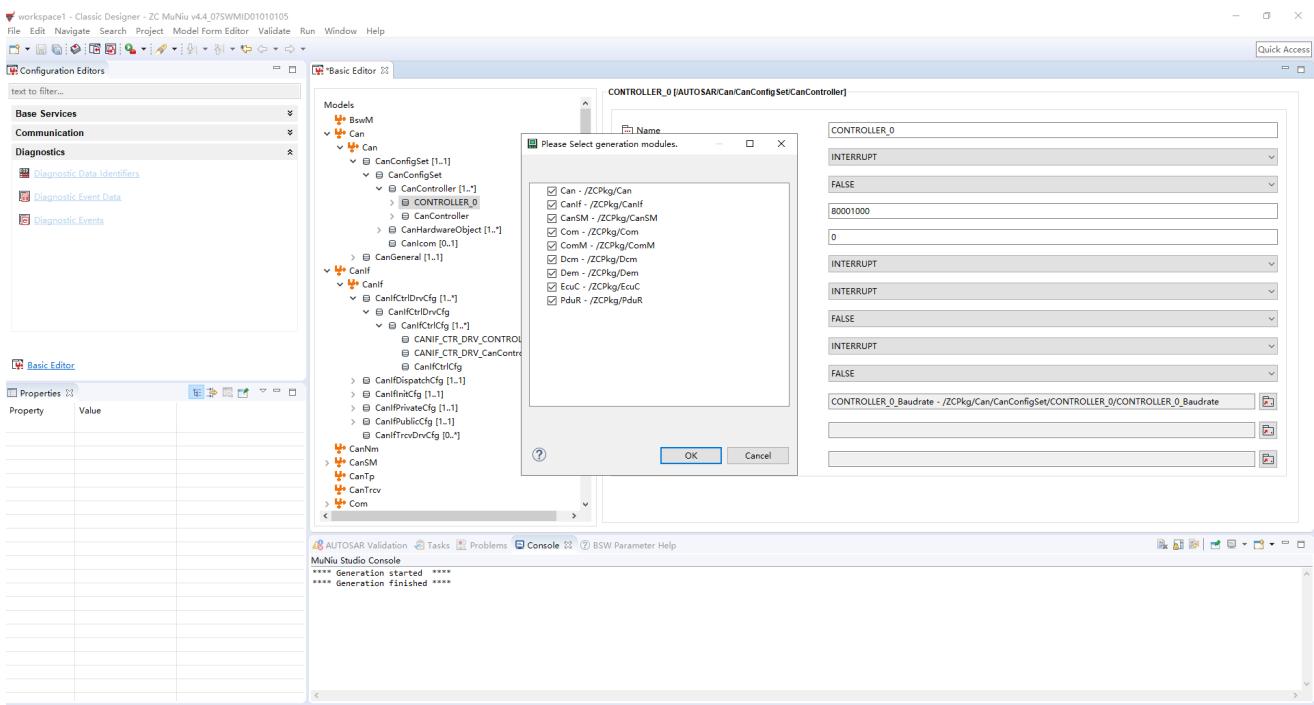
| 模块<br>Module                                    | 子模块<br>Submodule | 描述<br>Description   |
|---|------------------|---|
| <b>Memory Service<br/>(MEM)</b>                 | FEE              | Flash 的 EEPROM 模拟器<br>Implement the Basic Software Protocol Stack for Non-Volatile Storage Management |
|   | MEMIF            | 存储器抽象层接口  |
|   | NVM              | NVRAM管理器  |
| <b>通信服务<br/>Communication Service<br/>(COM)</b> | COM              | 通信<br>Communication   |
|   | AUTOSAR NM       | 网络管理接口<br>Network Management Interface  |
|   | OSEK NM          | OSEK网络管理<br>Network Management Interface  |
|   | PduR             | PDU路由<br>PDU Routing  |
|   | ComXf            | COM通信序列化<br>COM Based Transformer   |
|   | IpduM            | I-PDU多路复用<br>I-PDU Multiplexer  |
|   | LdCom            | 大数据信号通信<br>Large Data COM   |
|   | Nm               | 网络管理<br>Network Management  |
| <b>CAN通信<br/>CAN Communication</b>              | SecOc            | 安全车载通信<br>Secure Onboard Communication  |
|   | CANIF            | CAN接口<br>CAN Interface  |
|   | CANNM            | CAN网络管理<br>CAN Network Management   |
|   | CANSM            | CAN状态管理器<br>CAN State Manager   |
|   | CANTP            | CAN传输协议<br>CAN Transmission Protocol  |
|   | J1939Nm          | J1939网络管理<br>J1939 Network Management   |
|   | J1939Rm          | J1939请求消息管理   |

| 模块<br>Module                               | 子模块<br>Submodule  | 描述<br>Description   |
|--|---|---|
|  | J1939 Request Manager<br>J1939Tp<br>J1939 传输协议<br>J1939 Transmission Protocol |   |
| <b>ETH通信</b><br><b>ETH Communication</b>   | DolP<br>IP诊断协议<br>IP Diagnostic Protocol                                      | 实现ETH通信的AUTOSAR基础软件模块<br>Implement the AUTOSAR basic software module for ETH Communication. |
|  | EthIf<br>ETH接口<br>ETH Interface   |   |
|  | EthSM<br>ETH状态管理器<br>ETH State Manager  |   |
|  | Sd<br>服务发现<br>Service Discovery   |   |
|  | SoAd<br>Socket适配器<br>Socket Adapter   |   |
|  | TcpIp<br>TCP IP协议栈<br>TCP IP Protocol Stack                                   |   |
|  | UdpNm<br>UDP网络管理<br>UDP Network Management                                    |   |
| <b>复杂驱动</b><br><b>Complex Driver (CDD)</b> | SBC DRV<br>电源芯片驱动<br>Power Chip Driver  | 实现复杂驱动功能的AUTOSAR基础软件模块<br>Implement the AUTOSAR basic software module for Complex Driver    |
|  | BCCIC DRV<br>电池管理系统采样芯片驱动<br>Battery Management System Sampling Chip Driver   |   |
|  | Safety Frame<br>功能安全框架<br>Safety Frame  |   |
| .... ....                                  |   |   |

## 5.3 配置工具 Configuration Tool



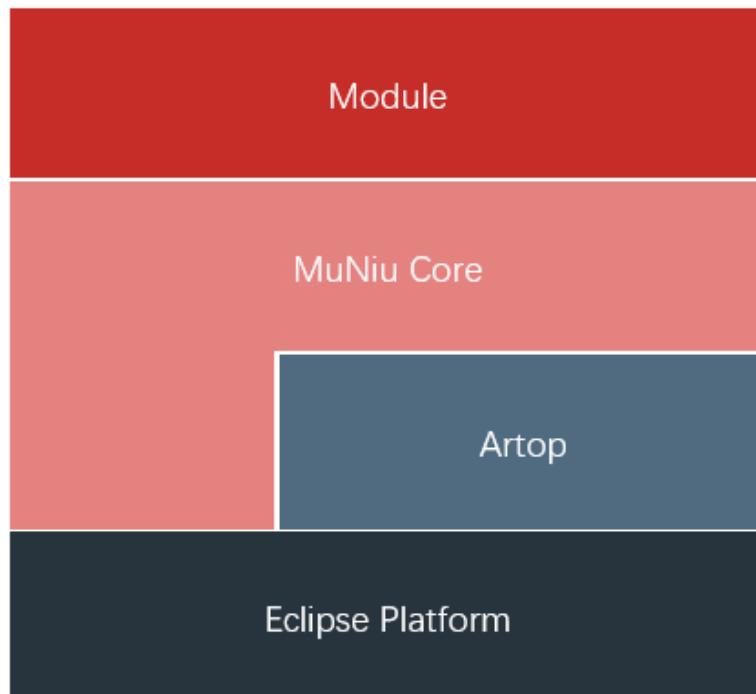
木牛配置工具主界面  
MUNIU CONFIGURATION TOOL MAIN INTERFACE



木牛配置工具生成配置代码  
MUNIU CONFIGURATION TOOL GENERATES CONFIGURATION CODE

为了满足客户的不同项目需求，提高基础软件平台的扩展性，木牛基础软件平台实现了各个模块可配置性，并且实现了配置工具。客户可根据不同需求，在配置工具上完成各个模块的配置工作，可生成配置代码文件，将生成的配置文件集成到工程中即可。

To meet the diverse project requirements of customers and enhance the scalability of the basic software platform, the MuNiu basic software platform has implemented the configurability of each module and has also developed a configuration tool. Customers can complete the configuration of each module according to different needs on the configuration tool, generate configuration code files, and integrate the generated configuration files into the project.



木牛配置工具架构  
ZC.MUNIU CONFIGURATION TOOL ARCHITECTURE

木牛基础软件平台的配置工具是基于 Eclipse 平台，并基于 ARTOP 架构，实现 AUTOSAR 模型和 ARXML 的解析。MuNiu Core 完成配置工具的 UI 界面，在 MuNiu Core 之上的 Module，实现 AUTOSAR 各个模块的配置。配置完成后，可生成各个模块的配置代码。

ZC.MuNiu basic software platform configuration tool is based on the Eclipse platform and is built on the ARTOP architecture, which implements the parsing of the AUTOSAR model and ARXML. ZC.MuNiu Core completes the UI interface of the configuration tool, and the Module on top of ZC.MuNiu Core realizes the configuration of each AUTOSAR module. After the configuration is completed, the configuration code for each module can be generated.

## 6 过程文档 PROCESS DOCUMENTATION

| 开发流程<br><br>Development<br>Process                                    | 文档描述<br><br>Documentation Description   |
|---|---|
| 需求收集<br><br>Requirement<br>Collection                                 | 客户需求文档<br>Customer Requirement Document   |
| 软件需求分析<br><br>Software<br>Requirement<br>Analysis                     | 需求分析文档<br>Requirement Analysis Document<br>软件需求追踪表<br>Software Requirement Traceability Matrix<br>问题沟通表<br>Issue Communication Form   |
| 软件架构设计<br><br>Software<br>Architectural<br>Design                     | 软件架构说明书<br>Software Architecture Specification<br>软件架构的追踪表<br>Software Architecture Traceability Matrix   |
| 软件详细设计和<br>单元设计<br><br>Software<br>Detailed Design<br>and Unit Design | 软件详细设计说明书<br>Software Detailed Design Specification<br>配置工具设计文档<br>Configuration Tool Design Document<br>软件详细设计追踪表<br>Software Detailed Design Traceability Matrix<br>软件详细设计评审表<br>Software Detailed Design Review Form |
| 软件单元测试<br><br>Software Unit<br>Testing                                | QAC 分析报告<br>QAC Analysis Report<br>Tessy 测试报告<br>Tessy Test Report<br>软件单元验证策略<br>Software Unit Verification Strategy   |
| 软件集成和集成<br>测试   | 集成策略<br>Integration Strategy<br>集成手册  |

| 开发流程<br>Development<br>Process               | 文档描述<br>Documentation Description  |
|--|--|
| Software Integration and Integration Testing | Integration Manual<br>集成测试策略<br>Integration Test Strategy<br>集成测试报告<br>Integration Test Report<br>资源分析报告<br>Resource Analysis Report |
| 软件系统测试<br>Software System Testing            | 系统测试报告<br>System Test Report<br>系统测试报告评审<br>System Test Report Review  |
| 发布<br>Release                                | 发布文档<br>Release Documentation  |

## 7 证书 CERTIFICATE



木牛软件著作权登记证书

MUNIU SOFTWARE COPYRIGHT REGISTRATION CERTIFICATE



公众号



业务联系

成为全球领先的汽车基础软件公司

To Be the Global Leading Automotive Basic Software Company

